Data sheet

| Z+F IMAGER [®] 5016 ² | Static scans | SLAM mode | |
|--|---|--|--|
| Measuring range | 0.3m - 365m | Min. 0.6 m | |
| Data acquisition rate | Max. 2.2 million pixels/s ³ | 550,000 pixels/s | |
| Resolution | Max. 100,000 pixels/profile | 10,000 pixels/profile | |
| Laser class | 1 | 1 | |
| | | | |
| Operational data | | | |
| Mounting | Upright orientation, e.g. for push-carts, small vehicles or robotic plat- forms, tilted orientation for backpack usage | | |
| Universal connection | 5/8" thread screw or 4x M5 Compatible with Z+F IMAGER Quick Mount | | |
| Camera | 2x 20MP, min distance 0.5m | 2x 20MP, min distance 0.5m | |
| Data storage | 1TB internal drive, 1TB removable SSD drive | | |
| Connectivity | Wifi 802.11 n/g standard, 1GBit | Wifi 802.11 n/g standard, 1GBit Ethernet | |
| Accuracy | Up to 2.5mm relative accuracy ¹ | | |
| Control data | Black and white targets, picked points, static scans | | |
| Output | E57, LAS/LAZ, PLY, PTS, ASC, ZFDB | | |
| | | | |
| Ambient conditions | | | |
| Environment | Indoor and outdoor usage | | |
| Operating temperatur | -10 °C +45 °C | | |
| Storage temperature | -20 °C +50 °C | | |
| Protection class | IP 54 | | |
| Power | | | |
| Batteries | uses the batteries of the static system, min. 2 / max. 4 batteries | | |
| Operating time | 3-4 hours scanning time (4 batteries) | | |
| Weight | 0.5 kg per battery | | |
| External Power | 24 VDC, 5 A | | |
| | | | |
| Dimensions and weights | | | |
| Cart setup | 262 x 262 x 146 mm, 3.5 kg | | |
| with camera | 351 x 262 x 612 mm, 4.7 kg | | |
| Backpack setupiv with camera | 380 x421 x 628 mm, 6.1 kg 380 x 421 x 1015 mm, 7.1 kg | | |
| Imager 5016 / A, with Quick Mount two or four batteries, each | 150 x 258 x 333 mm, 6.6 kg | | |
| two of tour patternes, each | 0.5 kg | | |

¹ 3D comparison result of SLAM point cloud to a mesh of static Z+F IMAGER 5016 scans, ca 550 m², SLAM data downsampled to 1cm, 80% of compared points within 2.5mm. No targets or static scans were used to optimize the result, only multiple loop closures. The result of 2.5mm should only be seen as an example of an achievable accuracy of a pointcloud, solely based on SLAM data, and cannot be guaranteed. In general, the accuracy depends on multiple factors, such as the scene geometry and well-distributed static features, the data acquisition process, postprocessing optimization of the dataset and additional support data, such as targets or static scans.

 $^2\,\text{More}$ details available in the Z+F IMAGER* 5016/A data sheet

³Z+F IMAGER[®] 5016 A

Z+F FlexScan 22

Mobile Mapping SLAM platform

+ Accurate tracking system
+ Cutting edge camera system
+ Suitable indicors and outdoors



+ Camera system

The Z+F FlexScan 22 is equipped with a panoramic camera to color map the mobile scan data.

+ Easy data collection

Static and mobile data is synchronized locally on an internal hard drive and also on a removable medium for backup and processing.

Highly accurate measurement results require static scans from multiple angles, whereas mobile solutions focus on efficiency.

The Z+F FlexScan platform developed by Zoller + Fröhlich combines the advantages of static scans with the efficiency of mobile systems. The perfect complement for any time-sensitive or large-scale application: AEC, facility management, process industries, heritage documentation and forensics.

+ Universal mounting

The Z+F FlexScan 22 can be used universally on different mobile systems. If the area or terrain is difficult to pass, the system can be used as a backpack to be able to climb stairs and ladders without any problems. If there are no big obstacles, the Z+F FlexScan 22 allows installation on mobile systems. For static scans, there is also the option of placing the system on tripods.

+ Project efficiency

The solution offered by Zoller + Fröhlich with the Z+F FlexScan 22 enables a project-adaptive and balanced level of documentation in order to be as cost-effective as possible.

Measurement accuracy for the highest demands

The Z+F FlexScan 22 benefits from the very high quality and range of the static high-end scanner Z+F IMAGER[®] 5016 and achieves an accuracy of up to 2.5 mm in the SLAM result. Each profile scanned with the Z+F FlexScan 22 has 10,000 points, which ensure finest details in the 3D model. For very high accuracy requirements, the SLAM data can be enhanced by adding control points or survey controls.

ZF

+ blue workflow[®]

The data is seamlessly integrated into the blue workflow[®] and Z+F LaserControl[®] or exported to standard formats for third-party software.