RIEGL miniVUX-SYS®

- complete miniaturized & lightweight UAV-based LiDAR system with RIEGL miniVUX-series LiDAR sensor integrated
- different IMU/GNSS options available
- various mounting options for highly flexible installation
- prepared for remote control via low-bandwidth data link
- prepared for interfacing with optional RGB camera(s), hyperspectral camera, multispectral camera, and thermal imaging sensor
- Integration Kit 600 or Integration Kit 300 available for straightforward system integration with selected multi-rotor UAV types

The *RIEGL* miniVUX-SYS is a complete laser scanning system of low weight and compact size for flexible use in UAV-based applications on a variety of UAV/UAS/RPAS.

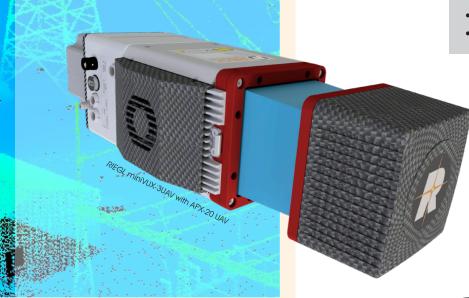
The system comprises a *RIEGL* miniVUX-series LiDAR sensor (*RIEGL* miniVUX-3UAV, *RIEGL* miniVUX-2UAV, *RIEGL* miniVUX-1UAV, *RIEGL* miniVUX-1LR or *RIEGL* miniVUX-1DL), an IMU/GNSS system (different versions available), and an optional RGB camera system.

The measurement performance of *RIEGL*'s UAV LiDAR sensors in combination with the Inertial Measurement Unit and the associated GNSS receiver results in survey-grade measurement accuracy.

The miniVUX-SYS is delivered with the necessary software tools for processing and geo-referencing of the acquired scan data, and processing of the IMU/GNSS data.

Typical applications include

- Agriculture & Forestry
- Glacier and Snowfield Mapping
- Archeology and Cultural Heritage Documentation
- Construction-Site Monitoring
- Landslide Monitoring



visit our website www.riegl.com



RIEGL miniVUX®-SYS with APX-15 UAV (e.g. for fixed-wing UAVs)

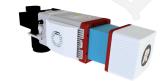
For this miniVUX-SYS solution, the APX-15 UAV¹⁾ IMU/GNSS unit is integrated in a small interface box which is attached to the rear part of the LiDAR sensor. Due to its compact and lightweight design and the total weight of approx. 2 - 2.8 kg (depending on scanner type, without camera(s)), the *RIEGL* miniVUX-SYS with APX-15 UAV is very well suited for an integration with UAV platforms offering limited / restricted weight and space conditions. Optionally, a single or a dual RGB camera system is available.

RIEGL miniVUX-3UAV / RIEGL miniVUX-2UAV / RIEGL miniVUX-1UAV / RIEGL miniVUX-1LR equipped with APX-15 UAV





with two Sony Alpha 6000 cameras (oblique mount)



with nadir-looking camera e.g. Sony Alpha 6000 camera or Sony A7R III or Sony A7R IV

integration of other 3rd party cameras possible ²⁾



with nadir-looking camera e.g. Sony Alpha 6000 camera

RIEGL miniVUX®-SYS with APX-20 UAV

(e.g. for fixed-wing, single-rotor or multi-rotor UAVs)

For this miniVUX-SYS solution, the new, higher-grade APX-20 UAV¹⁾ IMU/GNSS system is used. The LiDAR sensor is equipped with a specifically designed interface box accommodating the GNSS board stack as well as the camera trigger electronics. The IMU sensor is tightly coupled with the LiDAR sensor. With its weight of approx. 2.5 - 3.3 kg (depending on scanner type, without camera(s)), the *RIEGL* miniVUX-SYS with APX-20 UAV is universally applicable for an integration with more or less all types of UAVs that are capable of carrying this payload weight. Optionally, a single or a dual RGB camera system is available.

RIEGL miniVUX-3UAV / RIEGL miniVUX-2UAV / RIEGL miniVUX-1UAV / RIEGL miniVUX-1LR equipped with APX-20 UAV



with nadir-looking camera e.g. Sony Alpha 6000 camera or Sony A7R III or Sony A7R IV

integration of other 3rd party cameras possible²⁾

RIEGL miniVUX-1DL equipped with APX-20 UAV

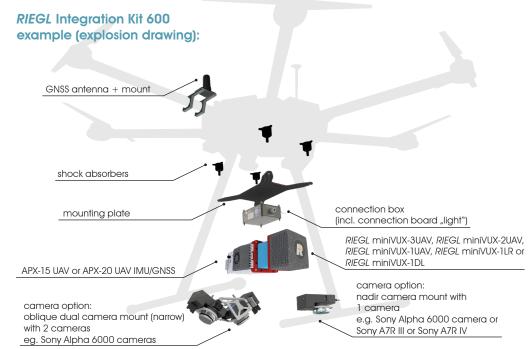


with nadir-looking camera e.g. Sony Alpha 6000 camera

- with two Sony Alpha 6000 cameras (oblique mount)
- 1) See technical details in the corresponding Applanix data sheet.
- 2) Multispectral camera, hyperspectral camera, thermal imaging sensor more information on request.

RIEGL Integration Kit 600 / Integration Kit 300 (e.g. for multi-rotor UAVs)

The *RIEGL* Integration Kit 600 as well as the Integration Kit 300 is an add-on to the miniVUX-SYS for its integration with your multi-rotor UAV, e.g. a DJI Matrice M600 or DJI Matrice M300 RTK. The package comes with an appropriate, shock absorbing mounting-kit, power supply module, GNSS antenna, GNSS antenna mount, and necessary cabeling for quick and straight forward integration.





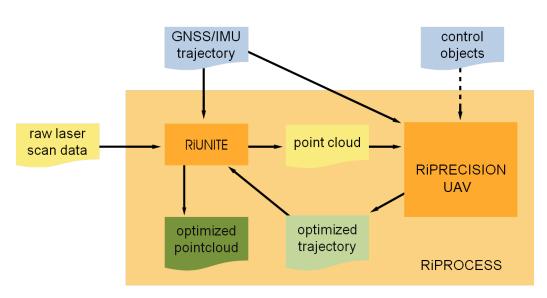
DJI Matrice M600 equipped with *RIEGL* miniVUX-SYS using *RIEGL* Integration Kit 600

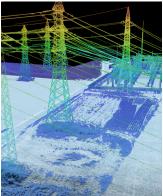


DJI Matrice M300 RTK equipped with *RIEGL* miniVUX-SYS using *RIEGL* Integration Kit 300

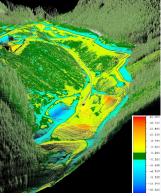
RIEGL miniVUX®-SYS - Processing Workflow and Scan Data Examples

Using *RIEGL*'s software suites (RiPROCESS, RiUNITE) and dedicated processing workflows with specialized alignment tools like RiPRECISION conducting the whole procedure of scan data alignment fully automatically, processing time can be reduced to a minimum. RiPROCESS can interface the optimized, georeferenced point cloud in further post-processing tools via LAS or other data exchanges in various user-defined coordinate systems.





power line surveying



cut and fill volume comparison of disposal site

Technical Data RIEGL miniVUX®-SYS

Scanner Performance

RIEGL UAV LiDAR Sensors (for details refer to the corresponding data sheet)		RIEGL miniVUX-2UAV	RIEGL miniVUX-1UAV		RIEGL miniVUX-1DL
Laser Pulse Repetition Rate (PRR)	up to 300 kHz	up to 200 kHz	100 kHz	100 kHz	100 kHz
Max. Effective Measurement Rate (meas./sec)	up to 200,000	up to 200,000	100,000	100,000	100,000
Max. Measuring Range, natural targets $\rho \geq 80\%$ $^{1)}$	330 m	330 m	330 m	500 m	260 m
Accuracy / Precision	15 mm / 10 mm	15 mm / 10 mm	15 mm / 10 mm	15 mm / 10 mm	15 mm / 10 mm
Field of View	up to 360° ²⁾	up to 360° 2)	up to 360° 2)	up to 360° 2)	up to 46°, ±23° off nadir
Max. Scan Speed	100 scans/sec	100 scans/sec	100 scans/sec	100 scans/sec	150 scans/sec

15

Max. Number of Targets per Pulse 3)

15

Applanix APX-15 LIAV 5)

15

IMU & GNSS 4)

	Applantix At X 20 0AV	Applantix At A 10 0AV
IMU Accuracy		
Roll, Pitch	0.015°	0.025°
Heading	0.035°	0.08°
IMU Sampling Rate	200 Hz	200 Hz
Position Accuracy (typ.)	0.02 - 0.05 m	0.05 - 0.1 m

Applanix APX-20 LIAV 5)

5

Interfaces

Configuration, Scan Data Output & Communication with External Devices GNSS Interface 6)

General IO & Control 7) Camera Interface Memory Card Slot

Serial Interface to External Devices

2 x LAN 10/100/1000 Mbit/sec WLAN IEEE 802.11 a/b/g/n

Serial RS-232 interface for data string with GNSS-time information TTL input for 1PPS synchronization pulse

2 x TTL input/output, 1 x Remote on/off

2 x GNSS RS-232 Tx & PPS, Power, Trigger, Exposure

for SDHC/SDXC memory card 32 GByte (can be upgraded to 64 GByte)

RIEGL miniVUX-1DL

typ. 43 W @ 75 revolutions/sec

 0°C up to $+40^{\circ}\text{C}$ (operation) $^{9)}$

-20°C up to +50°C (storage)

232 x 111 x 123 mm / approx. 2.44 kg

232 x 99 x 123 mm / approx. 2.4 kg

264 x 111 x 85 mm, approx. 2.8 kg

352 x 111 x 85 mm, approx. 3.3 kg

11 - 34 V DC

SPI (Serial Peripheral Interface)

6) internally available (not available with standard interface box)

7) 1x externally available with standard interface box

General Technical Data

RIEGL UAV LiDAR Sensors

(for details refer to the corresponding data sheet)

Power Supply Input Voltage Consumption

Main Dimensions (L x W x H) / Weight with Cooling Fan without Cooling Fan Temperature Range 8)

Humidity **Protection Class**

RIEGL miniVUX-SYS

Main Dimensions (L x W x H) and Weight with APX-15 UAV with APX-20 UAV

Integration Kit 600 / Integration Kit 300

Weight Camera(s)

Continuous operation at ambient temperature of $\geq 30^{\circ} C~(\geq 86^{\circ} F)$ requires a minimum amount of air flow at approx. 3 m/s. For applications where a 3 m/s air flow along the cooling fins cannot be guaranteed, the cooling fan has to be used.

RIEGL miniVUX-3UAV, -2UAV, -1UAV, -1LR

11 - 34 V DC

typ. 18 W @ 100 scans/sec

243 x 111 x 85 mm / approx. 1.6 kg 243 x 99 x 85 mm / approx. 1.55 kg -10°C up to +40°C (operation) -20°C up to +50°C (storage) max. 80 % non condensing @ 31°C

IP64, dust and splash-proof

264 x 111 x 85 mm, approx. 2.0 kg 352 x 111 x 85 mm, approx. 2.5 kg

approx. 0.7 kg/approx. 0.35 kg

optional, technical data depending on selected camera type

9) Valid for the initial start-up. After a warm-up phase, operation down to -10°C is also possible.



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Typical values for average conditions. Maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. In bright sunlight, the max. range is shorter than under overcast sky.

²⁾ Selectable. Consider limitations when integrated in kinemtatic systems.
3) If more than one target is hit, the total laser transmitter power is split and, accordingly, the achieveable range is reduced.

⁴⁾ In addition to the APX-15 UAV and the APX-20 UAV IMU/GNSS system, also a AP20 IMU/GNSS system with external control unit is optionally available. Corresponding details provided on request.

⁵⁾ See technical details in the corresponding Applanix datasheet.